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$$\mathcal{D}(R(\theta)) = e^{-i\mathbf{J}\cdot\boldsymbol{\Omega}\theta/\hbar} = \left(1 - \frac{i\mathbf{J}\cdot\boldsymbol{\Omega}}{\eta}\delta\theta\right)^N, \quad \delta\theta = \frac{\theta}{N}$$

$$\lim_{N\rightarrow\infty} \left(1 - \frac{x}{N}\right)^N = e^{-x}$$

$$[\mathbf{J}^2, J_z] = 0$$

$$\mathbf{J}^2|j, m\rangle = \lambda_j |j, m\rangle$$

$$J_z|j, m\rangle = m\hbar |j, m\rangle$$

$$J_-J_+ = \mathbf{J}^2 - J_z(J_z + 1)$$

$$0 = J_+|j, m_{\max}\rangle \Rightarrow \lambda_j - m_{\max}(m_{\max} + 1) = 0$$

$$\lambda_j - m_{\min}(m_{\min} - 1) = 0$$

$$m_{\min} = -m_{\max}$$

$$\lambda_j = j(j+1)$$

$$m = -j, -j+1, \dots, j-1, j$$

$j$  is an integer or an half integer.

$$\langle j, m|J_-J_+|j, m\rangle = \hbar^2(j(j+1) - m(m+1))\langle j, m|j, m\rangle$$

$$J_+|j, m\rangle = \hbar\sqrt{j(j+1) - m(m+1)}|j, m+1\rangle$$

$$J_-|j, m\rangle = \hbar\sqrt{j(j+1) - m(m-1)}|j, m-1\rangle$$

$$j = 1/2. \quad \mathbf{J}^2 = j(j+1) = \frac{1}{2} \cdot \frac{3}{2} = \frac{3}{4}.$$

$$|\mathbf{J}| = \sqrt{3/4}. \quad J_z = -\frac{1}{2}, +\frac{1}{2}.$$

$$\text{Spin 1: } \mathbf{J}^2 = 1(1+1) = 2.$$

$$\text{Limit } j \rightarrow \infty. \quad \mathbf{J}^2 \rightarrow \hbar^2 j(j+1) \approx \hbar^2 j^2.$$

$$[J_i, J_j] = \hbar i \varepsilon_{ijk} J_k$$

$$\mathbf{L} = \mathbf{r} \times \mathbf{p}$$

$$[L_i, L_j] = \hbar i \varepsilon_{ijk} L_k$$

$$\mathbf{R}^2 = x^2 + y^2 + z^2$$

$$[\mathbf{R}^2, L^2] = 0, \quad [\mathbf{R}^2, L_z] = 0$$

$|\mathbf{R}^2, L^2, L_z\rangle$  Spherical harmonics

$|p\rangle$  Fourier transforms

How does  $\mathbf{J}$  relate to spherical coordinates?

$$L_k = \sum_{ij} \varepsilon_{kij} r_i p_j$$

$$(x, y, z) = r(\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$$

$$L_i = i \varepsilon_{ijk} x_j \frac{\partial}{\partial x_k} = i \varepsilon_{ijk} x_j \left( \frac{\partial y_l}{\partial x_k} \right) \frac{\partial}{\partial y_l} = i \varepsilon_{ijk} x_j \left( \frac{\partial(x_1, x_2, x_3)}{\partial(y_1, y_2, y_3)} \right)_{lk}^{-1} \frac{\partial}{\partial y_l}$$

$$\sqrt{\frac{4\pi}{3}} r Y_1^0(\theta, \varphi) = z$$

$$\sqrt{\frac{4\pi}{3}} r \left( Y_1^1 + Y_1^{-1} \right) \frac{1}{\sqrt{2}} = x$$

$|j_1, m_1\rangle \otimes |j_2, m_2\rangle$ .  $\{|j_1, j_2, m_1, m_2\rangle\}$  = basis for Hilbert space.

$$\mathcal{D}(R_\Omega(\theta)) \left[ |\alpha_1\rangle \otimes |\alpha_2\rangle \right] = (\mathcal{D}_1(R) |\alpha_1\rangle) \otimes (\mathcal{D}_2(R) |\alpha_2\rangle) = (\mathcal{D}_1(R) \otimes \mathcal{D}_2(R)) (|\alpha_1\rangle \otimes |\alpha_2\rangle)$$

$$(2 \times 2) \otimes (3 \times 3) = (6 \times 6).$$

$$\begin{aligned} \mathcal{D}(\delta\theta) &= \exp\left(-i \mathbf{J}_1 \cdot \boldsymbol{\Omega} \frac{\delta\theta}{\hbar}\right) \otimes \exp\left(-i \mathbf{J}_2 \cdot \boldsymbol{\Omega} \frac{\delta\theta}{\hbar}\right) = \left(\mathbb{I} - i \mathbf{J}_1 \cdot \boldsymbol{\Omega} \frac{\delta\theta}{\hbar}\right) \otimes \exp\left(\mathbb{I} - i \mathbf{J}_2 \cdot \boldsymbol{\Omega} \frac{\delta\theta}{\hbar}\right) = \\ &= \mathbb{I} \otimes \mathbb{I} - i \mathbf{J}_1 \cdot \boldsymbol{\Omega} \frac{\delta\theta}{\hbar} \otimes \mathbb{I} - \mathbb{I} \otimes i \mathbf{J}_2 \cdot \boldsymbol{\Omega} \frac{\delta\theta}{\hbar} + \dots = \\ &= \mathbb{I}_{6 \times 6} - i (\mathbf{J}_1 \otimes \mathbb{I} + \mathbb{I} \otimes \mathbf{J}_2) \cdot \boldsymbol{\Omega} \frac{\delta\theta}{\hbar} \\ &= \mathbb{I} - i \mathbf{J}_{\text{tot}} \otimes \boldsymbol{\Omega} \frac{\delta\theta}{\hbar} \end{aligned}$$

$$\mathbf{J}_{\text{tot}} = \mathbf{J}_1 \otimes \mathbb{I} + \mathbb{I} \otimes \mathbf{J}_2 = [\text{this is sloppily written as}] = \mathbf{J}_1 + \mathbf{J}_2$$